

# Visualizing

# Tensors

and their Algebra,

with applications for

Electromagnetism and Relativity

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# **All vectors are NOT created equal.**

## **The directed quantities**

- *displacements*
- *gradients*
- *“normals” to surfaces*
- *fluxes*

**appear to be so due to symmetries**

- *dimensionality of the vector space*
- *orientability of the vector space*
- *existence of a “volume-form”*
- *existence of a “metric tensor”*
- *signature of the metric*

**These symmetries blur the  
true nature of the  
directed quantity.**

## What is vector?

“something with a magnitude and direction”?

Well... no... that's a “Euclidean Vector”  
(a vector with a metric [a rule for giving the lengths of vectors and the angles between vectors])

Not all vectors in physics are Euclidean vectors.

A vector space is a set with the properties of

- addition  
*(the sum of two vectors is a vector)*
- scalar multiplication  
*(the product of a scalar and a vector is a vector)*

Elements of this set are called vectors.

## What is tensor?

A tensor [of rank  $n$ ] is a multi-linear function of  $n$  vectors (which, upon inputting  $n$  vectors, produces a scalar).

They are useful for describing anisotropic (direction-dependent) physical quantities. For example,

- metric tensor
- moment of inertia tensor
- elasticity tensor
- conductivity tensor
- electromagnetic field tensor
- stress tensor
- riemann curvature tensor

If the vector has, for example, 3 components, then a rank- $n$  tensor has  $3^n$  components.

(If you think about a vector as a column matrix, a tensor can be thought of as a [generalized] matrix. But that's not really a good way to think about them.)

# In three dimensions, there are eight types of directed quantities.

SIMULTANEOUS IDENTIFICATIONS

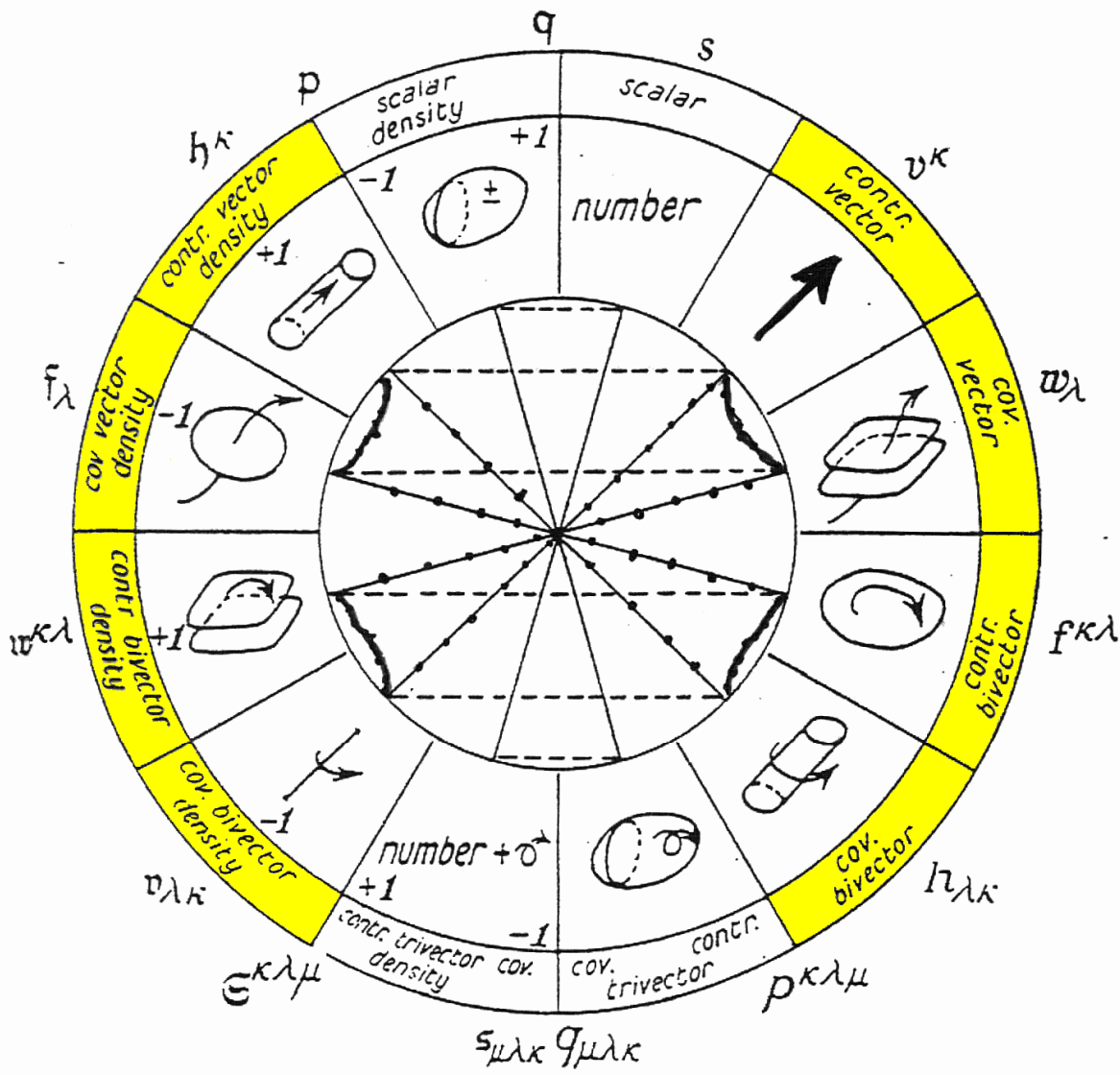


FIG. 13.

From J.A. Schouten, *Tensor Calculus for Physicists*.

A point worth re-emphasizing:

**Not all “vectors” in physics were “born as vectors”... they may have been born as covectors (1-forms), bivectors, or 2-forms.**

**Can we gain some physical and geometrical intuition by visualizing the natural form of these directed-quantities?**

# VECTORS $V^a$



## Representations

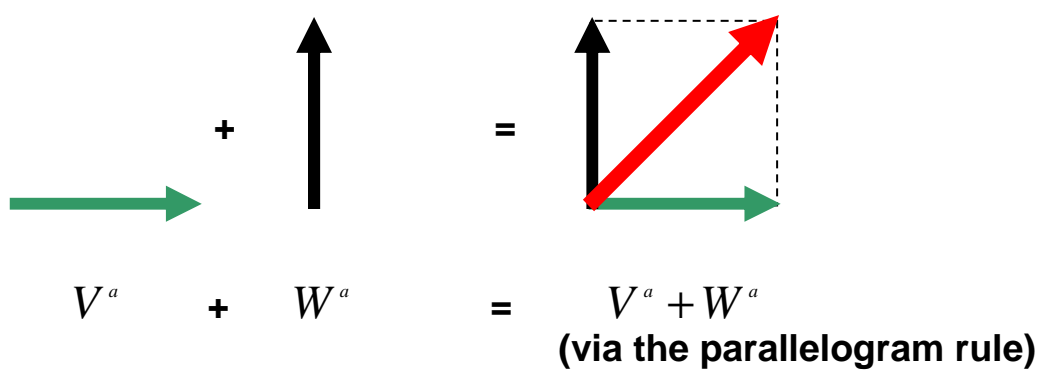
- ordered PAIR OF POINTS with finite separation
- directed line-segment (“an ARROW”)

The separation is proportional to its size.

*(irrelevant features: thickness of the stem, size of the arrowhead)*

## Examples:

• displacement	$r^a$	[in meters] as in	$U = \frac{1}{2} k_{ab} r^a r^b$
• electric dipole moment	$p^a = qd^a$	[in Coulomb-meters] as in	$U = -p^a E_a$
• velocity	$v^a$	[in meters/sec] as in	$K = \frac{1}{2} m_{ab} v^a v^b$
• acceleration	$a^a$	[in meters/sec <sup>2</sup> ] as in	$F_a = m_{ab} a^b$



# COVECTORS (ONE-FORMS) $\omega_a$

## Representations

- ordered PAIR OF PLANES ( $\omega_a V^a = 0$  and  $\omega_a V^a = 1$ ) with finite separation
- ("TWIN-BLADES")

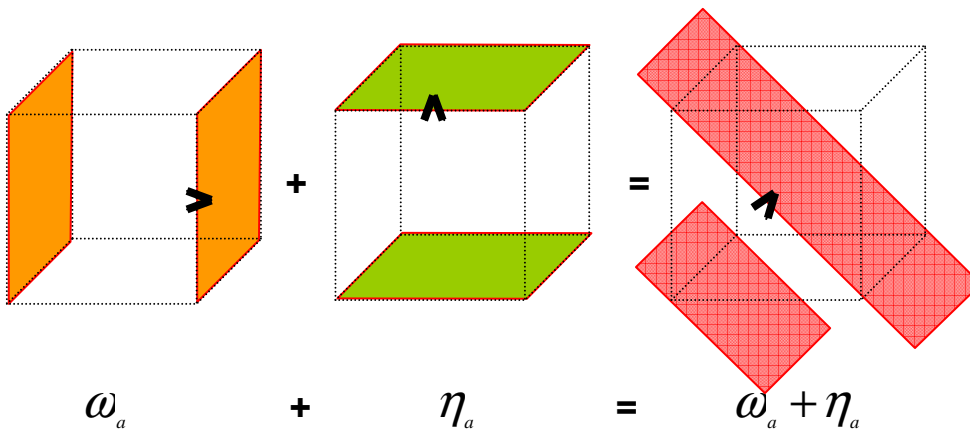
The separation is inversely-proportional to its size.

a pair of neighboring equipotential surfaces

(irrelevant features: size, shape, and alignment of the planar surfaces)

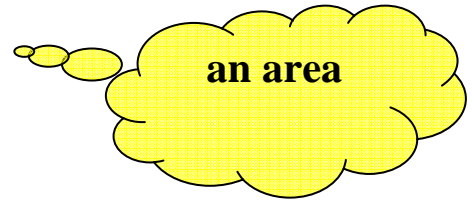
## Examples:

- gradient  $\nabla_a f$  [in  $[[f]] \cdot \text{meters}^{-1}$ ]
- conservative force  $F_a = -\nabla_a U$  [in Joules/meter] as in  $U = -p^a E_a$
- linear momentum  $"p_a = \frac{\hbar}{\lambda^a}" = \hbar k_a$  [in action/meter]
 
$$p_a = \frac{\partial S}{\partial q^a} = \frac{\partial L}{\partial \dot{q}^a} \quad p_a = -\frac{\partial H}{\partial q^a} = F_a$$
- electrostatic field  $E_a = -\nabla_a \phi$  [in Volts/meter] as in  $\phi = -\int_\gamma E_a$
- magnetic field  $\tilde{H}_a$  [in Amperes/meter] as in  $i_{\text{enclosed}} = \oint_{\partial A} \tilde{H}_a$



(via the co-parallelogram rule)

# BIVECTORS $A^{ab}$



## Representations

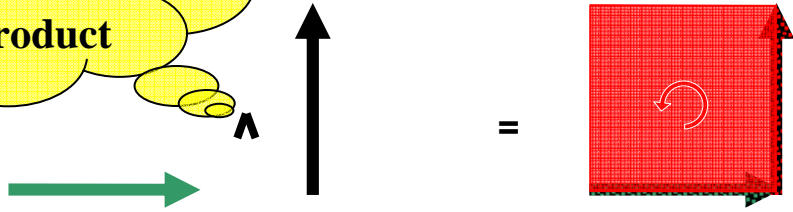
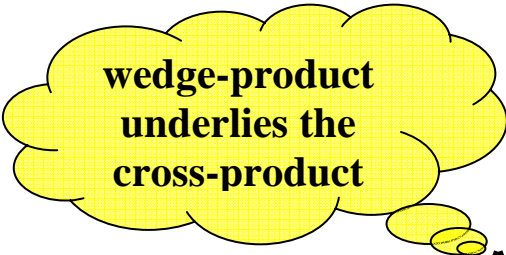
- ordered PAIR OF VECTORS (via the wedge product)
- directed two-dimensional planar region (“an AREA”)

The area is proportional to its size.

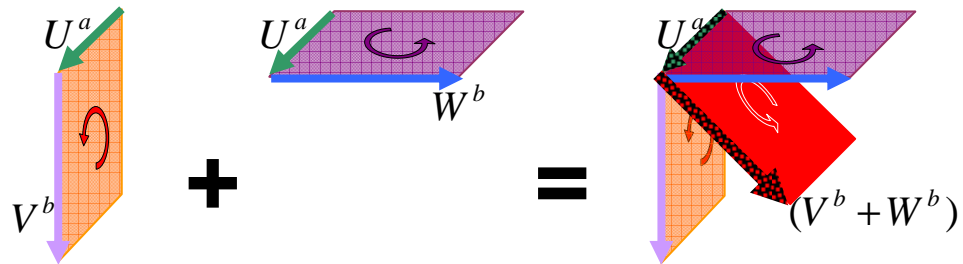
*(irrelevant features:  
shape of the planar surface)*

## Examples:

- area  $A^{ab}$  [in meters<sup>2</sup>] as in  $A^{ab} = l^{[a} w^{b]}$
- force-couple (zero net-force “moment”) [in (Newton/meter)-meter<sup>2</sup>]  $M^{ab} = r^{[a} F^{b]}$
- magnetic dipole moment  $\mu^{ab} = iA^{ab}$  [in Ampere-meter<sup>2</sup>] as in  $U = -\mu^{ab} B_{ab}$

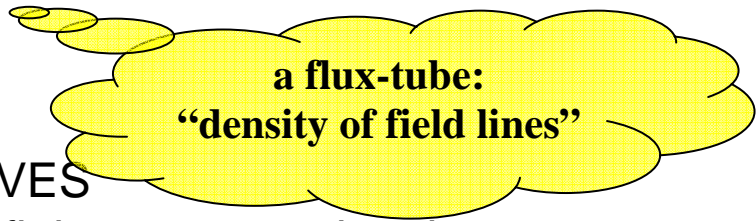


$$V^a \wedge W^a = V^{[a} W^{b]}$$



$$U^{[a} V^{b]} + U^{[a} W^{b]} = U^{[a} (V^{b]} + W^{b]})$$

# TWO-FORMS $\beta_{ab}$



## Representations

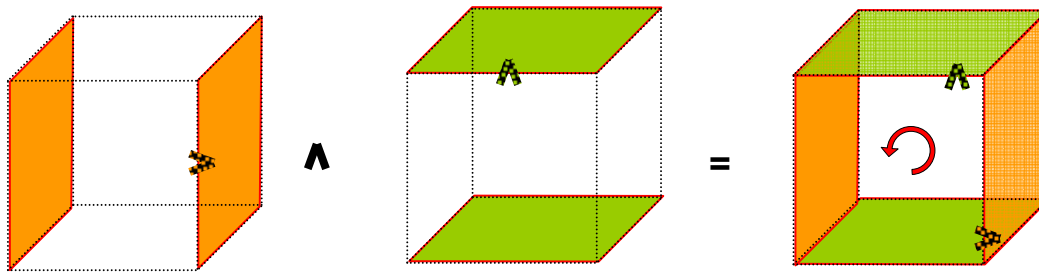
- ordered PAIR OF CLOSED CURVES
- directed cylinder (“a TUBE”) with finite cross-sectional area

The cross-sectional area is inversely-proportional to its size.

*(irrelevant features: shape of the cross-section, length of the tube)*

## Examples:

- magnetic induction  $B_{ab}$  [Weber/meter<sup>2</sup>=Tesla]  
(magnetic flux per cross-sectional area) as in  $\oiint_{\partial V} B_{ab} = 0$
- electric induction  $\tilde{D}_{ab}$  [Coulomb/meter<sup>2</sup>]  
(electric flux per cross-sectional area) as in  $\oiint_{\partial V} \tilde{D}_{ab} = 4\pi q_{enclosed}$
- current density  $\tilde{j}_{ab}$  [Ampere/meter<sup>2</sup>]  
(charge flux per cross-sectional area) as in  $\oint_{\partial A} \tilde{H}_a = \frac{\partial}{\partial t} \iint_A \tilde{D}_{bc} + 4\pi \iint_A \tilde{j}_{bc}$
- Poynting vector  $\tilde{S}_{ab} = \frac{1}{4\pi} E_{[a} \tilde{H}_{b]}$  [Watt/meter<sup>2</sup>]  
(energy flux per cross-sectional area)



$\alpha_a$

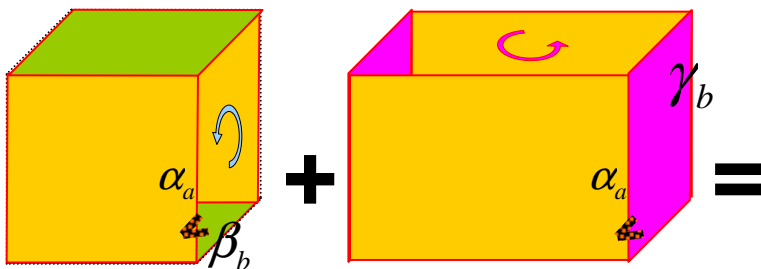
$\wedge$

$\beta_a$

$=$

$\alpha_{[a} \beta_{b]}$

$(\beta_b + \gamma_b)$



$\alpha_{[a} \beta_{b]}$

$+$

$\alpha_{[a} \gamma_{b]}$

$=$

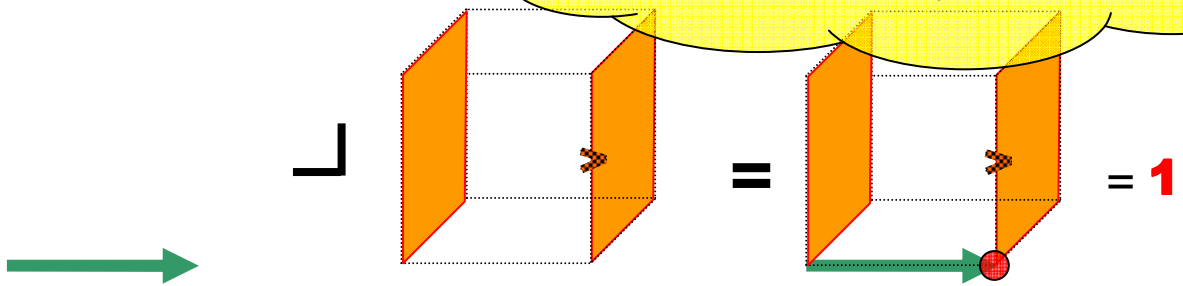
$\alpha_{[a} (\beta_b + \gamma_b)$



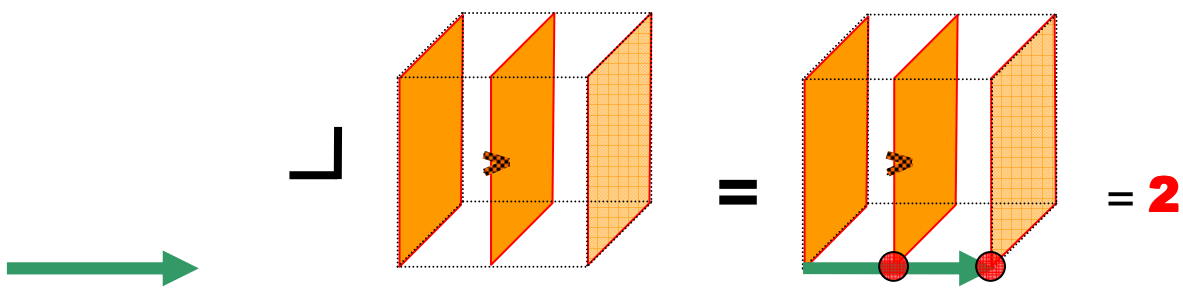
# TRANSVECTION / INNER PRODUCT

(nonmetrical  
“dot product”)

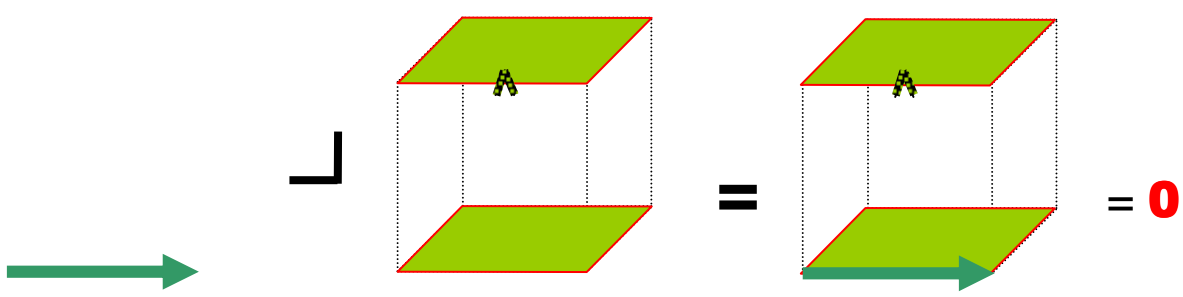
underlies “potential difference”

$$\Delta V = - \int_{\gamma} E \cdot d\vec{l}$$


$$V^a \lrcorner \omega_a = V^a \omega_a = 1$$



$$V^a \lrcorner 2\omega_a = V^a(2\omega_a) = 2$$



$$V^a \lrcorner \beta_a = V^a \beta_a = 0$$

In *Gravitation* (Misner-Thorne-Wheeler),  
 this operation is described as counting the “bongs of a bell”.

# METRIC TENSOR

# $g_{ab}$

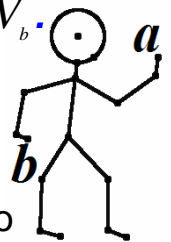
A metric tensor is a symmetric tensor that can be used to assign “magnitudes” to vectors.

$$\|V\|^2 = g_{ab} V^a V^b$$

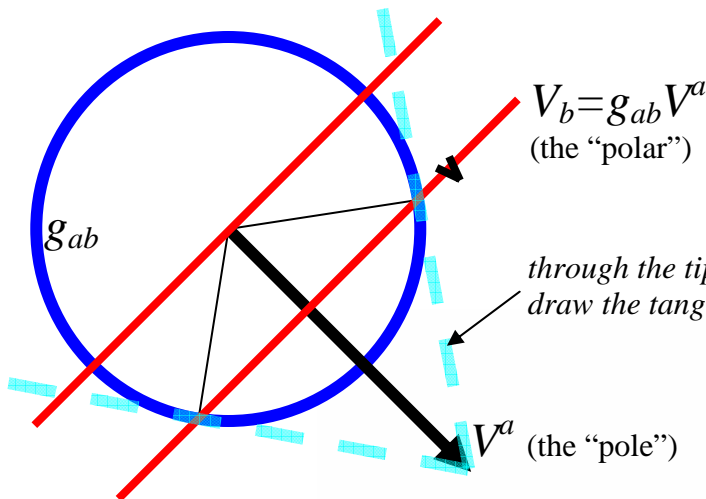
A metric tensor can also provide a rule to identify a vector with a unique covector. The vector and its covector are “duals” of each other with this metric.

Given a vector  $V^a$ , in the presence of a metric, we can form the combination  $g_{ab} V^a$ , which is a covector denoted by  $V_b$ .

This is known as “index lowering”, a particular move when performing “index gymnastics”.



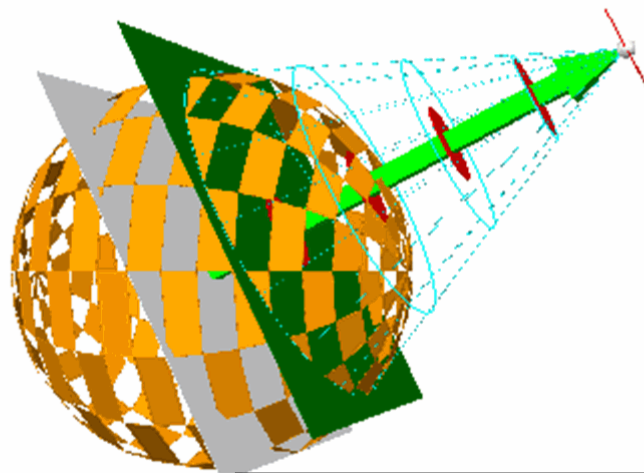
## the Euclidean metric:



This construction is due to W. Burke, *Applied Differential Geometry*. (See also Burke, *Spacetime, Geometry, and Cosmology*.)  
[First due to Schouten (1923)?]

`[ 2.00 , 1.00 , 0.00 ]`  
`sq-norm=5.0000`

A vector of square-length 5 with a Euclidean metric.



Note that  $V^a (g_{ab} V^b) = (\text{"length of } V^a\text{"})^2$ .  
Here  $V^a (g_{ab} V^b) = 5$ .

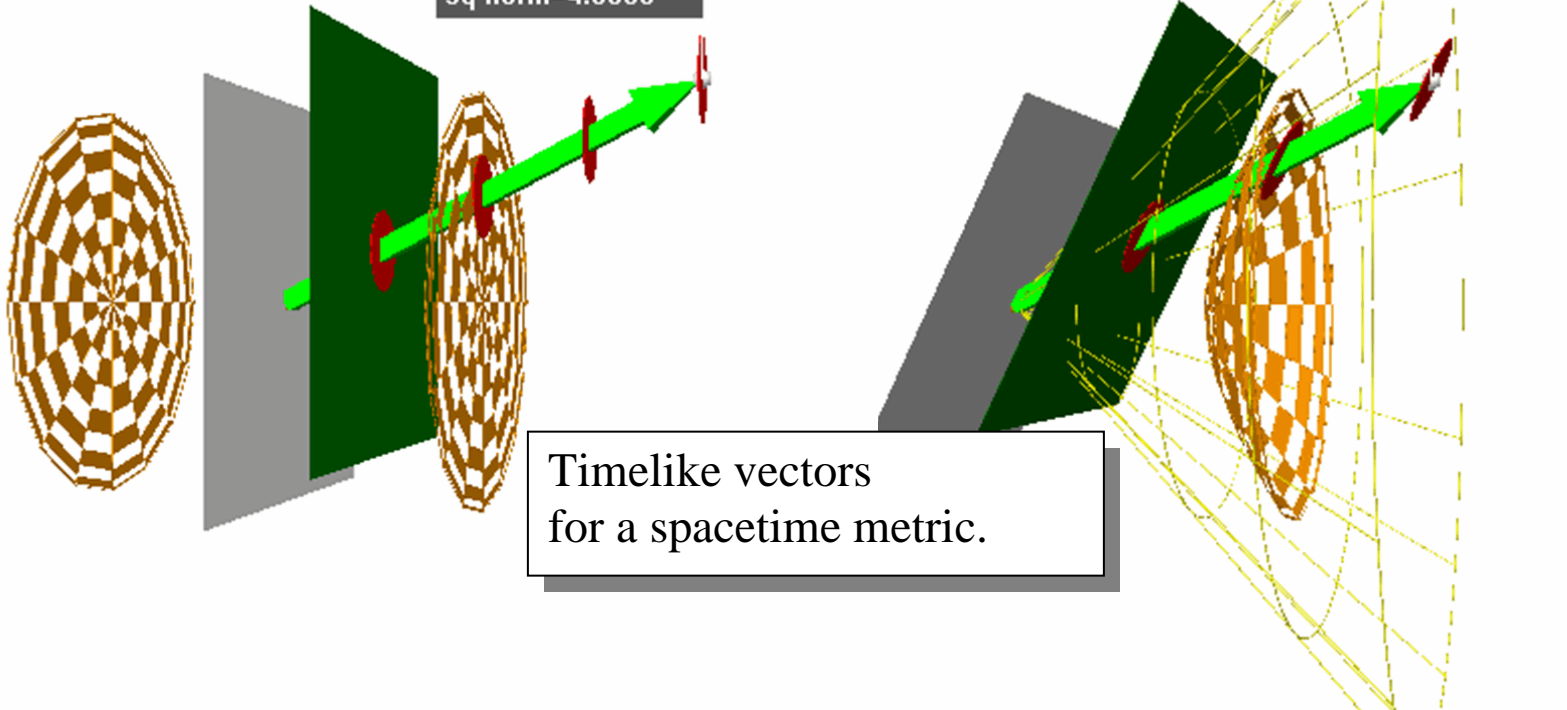
A similar pole-polar relationship can be demonstrated for

## Galilean

## Minkowski

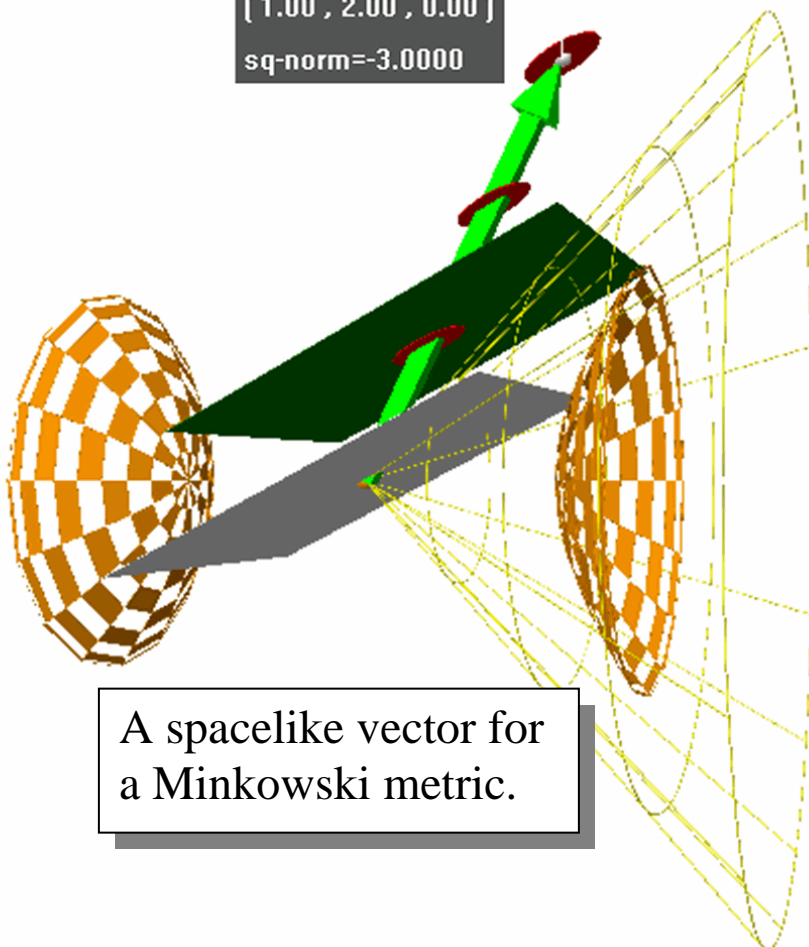
[ 2.00 , 1.00 , 0.00 ]  
sq-norm=4.0000

[ 2.00 , 1.00 , 0.00 ]  
sq-norm=3.0000



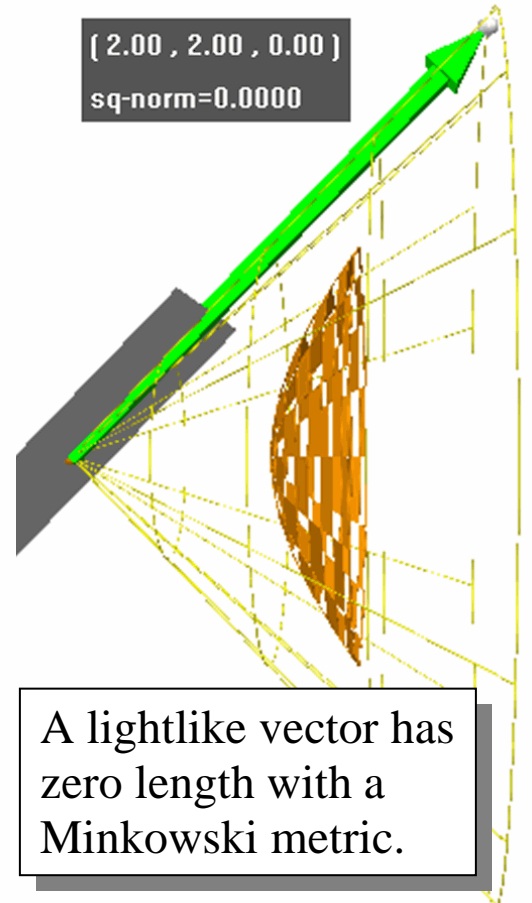
Timelike vectors  
for a spacetime metric.

[ 1.00 , 2.00 , 0.00 ]  
sq-norm=-3.0000



A spacelike vector for  
a Minkowski metric.

[ 2.00 , 2.00 , 0.00 ]  
sq-norm=0.0000



A lightlike vector has  
zero length with a  
Minkowski metric.

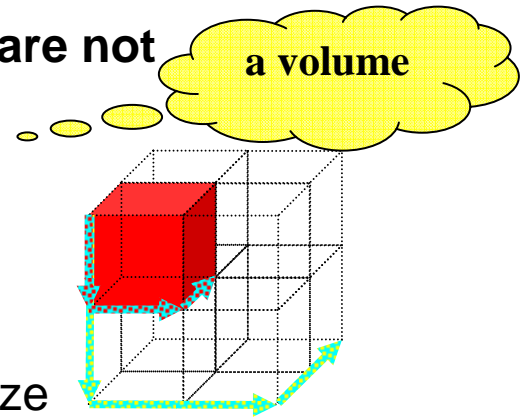
In three dimensional space, the following are not directed-quantities.

## TRIVECTORS $V^{abc}$

### Representations

- ordered TRIPLE OF VECTORS
- sensed regions (“a VOLUME”) with finite size

The volume is proportional to its size.



(irrelevant features:  
shape of volume)

### Examples:

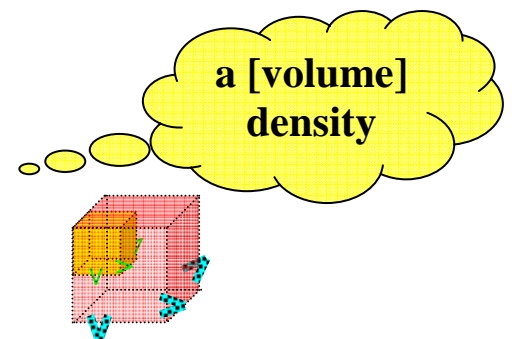
- volume  $V^{abc}$  [in meters<sup>3</sup>] as in  $V^{abc} = l^a w^b h^c$

## THREE-FORMS $\gamma_{abc}$

### Representations

- ordered TRIPLE OF COVECTORS
- cells (“a BOX”) which contain a finite volume

The enclosed-volume is inversely-proportional to its size.



(irrelevant features:  
shape of volume)

### Examples:

- charge density  $\tilde{\rho}_{abc}$  [in Coulombs/meter<sup>3</sup>] as in

$$q = \iiint_V \tilde{\rho}_{abc}$$

- energy density  $\tilde{u}_{abc}$  [in Joules/meter<sup>3</sup>] as in

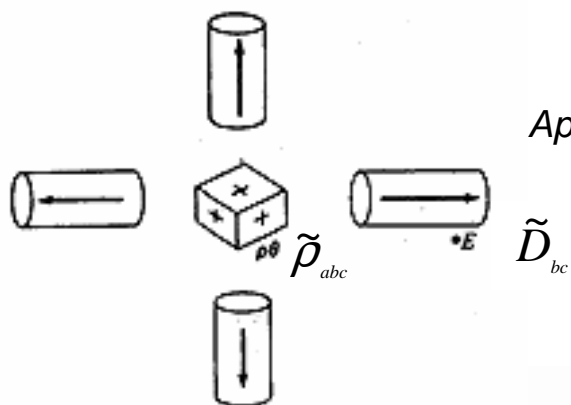
$$\tilde{u}_{abc} = \frac{1}{8\pi} E_{[a} \tilde{D}_{bc]}$$

## VOLUME FORM $\epsilon_{abc}$

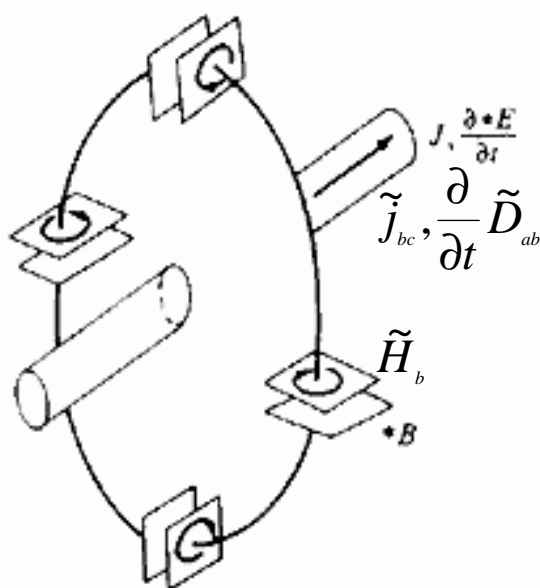
Specifying a **volume form** provides a rule to identify a vector with a unique two-form (in three dimensions), and vice versa. Vectors that are obtained from [ordinary] two-forms in this way are known as **pseudovectors**. (Some two-forms can be obtained from bivectors when a **metric tensor** is specified.)

# MAXWELL EQUATIONS FOR ELECTROMAGNETISM

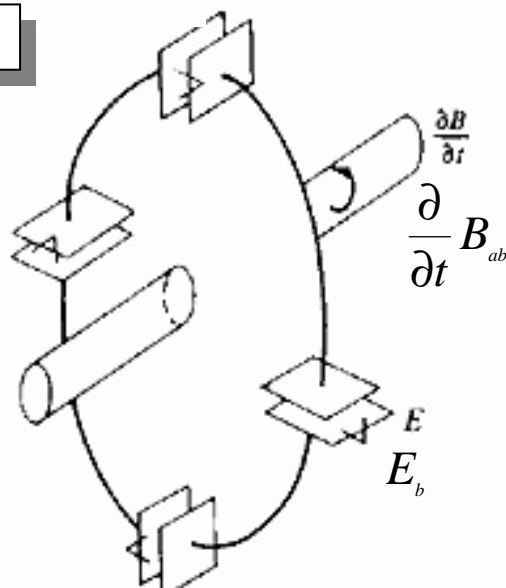
These diagrams are from  
W. Burke,  
*Applied Differential Geometry.*



Gauss



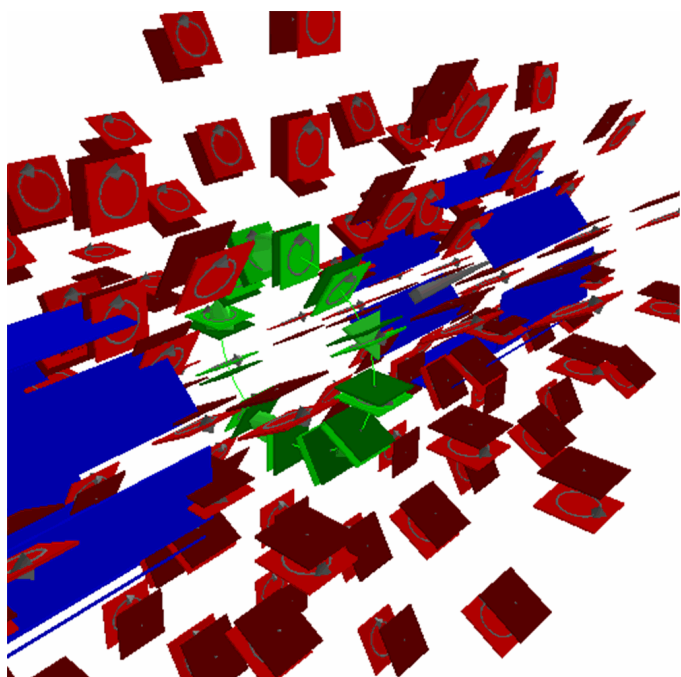
Ampere-Maxwell



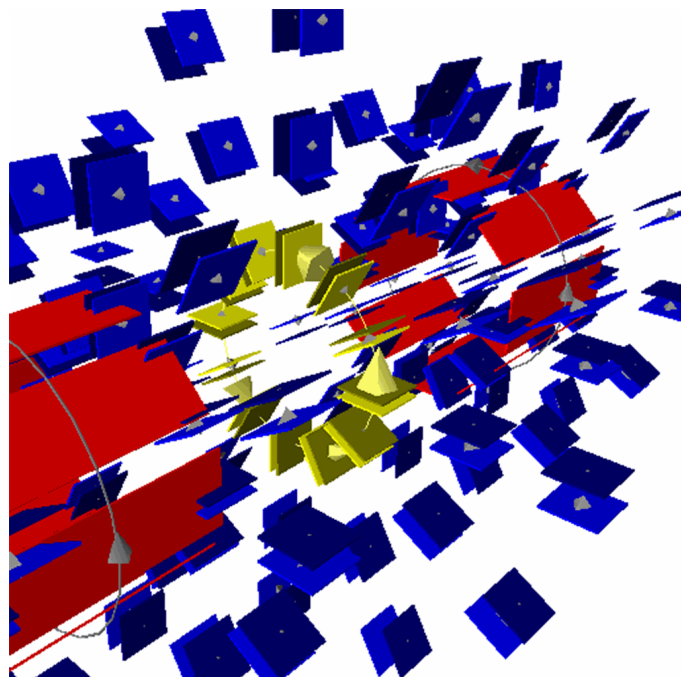
Faraday

To see these rendered in three dimensions, visit my  
**VRML Gallery of Electromagnetism** (1996)  
[physics.syr.edu/courses/vrml/electromagnetism/](http://physics.syr.edu/courses/vrml/electromagnetism/)

Hopefully soon, it will be available on my VPYTHON page  
[physics.syr.edu/~salgado/software/vpython/](http://physics.syr.edu/~salgado/software/vpython/)



**Ampere-Maxwell**



**Faraday**

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